

## XLX ENO II

### Heavy-Duty Work-Class ROV

The Perry® XLX EVO II is a compact, heavy-duty work-class hydraulic ROV, complementing the Perry XLX-C series of compact heavy-duty work-class ROVs.

The Perry XLX EVO II ROV system represents the latest evolution in the highly successful Perry XL series. The XLX EVO II features significantly enhanced performance across the full range of demanding intervention and survey tasks without compromise to the outstanding reliability for which the XL series of vehicles is renowned throughout the world.



3000 msw (option 4000 msw) Depth Rating

Power 200 hp (150 kw)

Through Frame Lift 3000 kg

**Control System** ICE® Unity Real Time Control System with GHz

Optical Link, Ethernet Telemetry and

**Graphical Diagnostics** 

**Control Modes** Heading, Heading Survey, Depth, Altitude,

Park, Dynamic Positioning with mid-water

Station Keeping, Waypoint Follow, Pitch, Roll, Cruise and Dynamic Braking

**Payload Capacity** 400 kg minimum

### Video, Serial, Power & Fibre Optic Channels

- Standard Definition Real-time Composite Video Channels (8)
- Individually dimmable light channels (6 typ)
- Dedicated serial and power channels for HPU, Valve Packs, Gyro, Depth, Altimeter/DVL, OA Sonar, Manipulator, Responder trigger
- Spare RS232/RS485 Serial Channels (7 typ)
- Single-mode Fibres: to Vehicle (2), to TMS (1)
- Spare CWDM Channels (4+8)
- Current Monitoring & Protection on each Power Channel
- 120 Vac 20 A dedicated tool supply

### Advanced interactive graphical diagnostics

**Control System** 

- User configurable GUI
- Ergonomic pilot/co-pilot control chairs combining touch screen and physical switch control interfaces

Utilizes the revolutionary ICE®

Unity Integrated Control Engine

Intuitive Graphic User Interface

Video Wall (As specified by client)

### **Typical Surface Power** Distribution

- 240 kVA Transformer for Vehicle **Hydraulics**
- 8.5 kVA Transformer for Vehicle Electronics (7.4 kVA at ROV)
- 15 kVA Transformer for TMS HPU
- 1.5 kVA Transformer for TMS Electronics (0.9 kVA at TMS)
- Ground fault detection circuits
- Deck cable interface
- CB, O/L and current/voltage sensors/meters









# XLX ENO II

### Heavy-Duty Work-Class ROV

#### **Dimensions & Performance**

Length: 3605 mm Width: 1905 mm Height: 2105 mm

Depth Rating: 3000 m (4000 m option)

Weight in Air: 5300 kg

Payload Capacity: 400 kg minimum

Through Frame Lift: 3000 kg

Fwd Lower Load Capacity: 250 kg at 250 mm Fwd Upper Load Capacity: 250 kg at 500 mm Aft Load Capacity: 300 kg at 500 mm Sides Load Capacity: 150 kg at 250 mm

Power Pack: 200 hp (150 kw)

Main Hydraulic System: 320 l/min @ 240 bar (60 Hz)

Thrusters Horizontal: 4 x 380 mm Thrusters Vertical: 4 x 300 mm Bollard Pull-Nominal (with 60 Hz supply) Forward: 1050 kgf Lateral: 1050 kgf

Auto Functions (Heading, Depth, Altitude, Park, Dynamic

940 kgf

Position)

Vertical (up/down):

**Heading Control:** ± 0.5° Pitch & Roll Control: ± 2.0° Depth Control: ±100 mm Altitude Control: ±100 mm **Auto Position** ±100 mm

(Achievable with suitable sensor e.g. SPRINT-Nav 300)

#### **Standard Equipment**

 Cameras Up to 8 Cameras (EMCCD/SIT

equiv./near SIT low light B/W, colour, zoom/fixed, manipulator,

light ring, HD (3 max), etc.)

Lights Up to 6 individual dimmable lights. Pan & Tilts Hydraulic SA-A-5735-MAS (2 fwd.)

Obstacle Avoidance Sonar or Multibeam Acoustic Camera

Heading, Pitch & Roll Sensor

Depth Sensor Digiquartz (±0.01%)

Doppler Velocity Log

 Main Valve Pack Bidirectional 10-Station (12 I/min,

each proportional flow, remote pressure selection 2 banks of 5

stations)

7 Function Manipulator (master slave control)

5 Function Grabber

RF Beacon, Emergency Xenon Flasher

### **System Options**

stem 238 L/min @ 240 bar, 60 Hz Option 200 L/min @ 260 bar, 60 Hz Auxiliary Hydraulic System

Bidirectional 10-Station (12 L/min, each Aux. Valve Pack proportional flow. Remote pressure

selection - 2 banks of 5 stations)

 High Flow VP Bidirectional 2 or 4-Station (25, 75, 140

or 150 L/min, each proportional pressure & flow, integrated torque tool

control)

 Water Filter Cardev (Main and Auxiliary) RS232/RS485 & power channels, Survey JB

camera channels, light channels, space

for high bandwidth interfaces

Gigabit Ethernet/PECL Interfaces for IP High speed data

cameras, Multibeam sonars, Profilers,

DVI

INS (Sonardyne SPRINT-Nav standard option or consult FET for

other units)

Transponders / responders

Workskids (not supplied)

Survey & Bathymetric suites

Suction Pile System

Jetting Module

Variable Ballast Module

Tool Interface Module

Control

Integrated Control Chairs

Sonar Computer, Keyboard & Topside Processor Unit

4 channel DVR unit (SD, HD or both)

Wired / wireless Deck Communications

3D Training Simulator with General & User Specific Scenarios

Tether Management System

Top hat or Garage

Type 4 up to 440m of Ø35mm / 750m of Ø27mm Tether

Type 5 up to 750m of Ø35mm / 1150m of Ø27mm Tether

Type 6 up to 1000m of Ø35mm / 1500m of Ø27mm Tether

Main Umbilical

Armoured or soft

Surface Handling

A-Frame / Cursor / Crane Jib-head Pulley

Winch

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The specification details are illustrative and are for marketing purposes only. Actual equipment may be different as a result of product improvement or other reasons. Specific interface and performance information should be reconfirmed at time

of order placement. SU1057.01.24







